

Needham, VDGAF, Chapter 31, Exercise 4, p. 335.

Palmer, September 13, 2024, 8 am, PT

4. Geodesic Curvature via Intrinsic Differentiation. Let $\mathbf{v}$ be the velocity of a particle traveling at unit speed along a trajectory K over the surface S of some peelable fruit. If o is the launch point, let $(\mathbf{e}_1, \mathbf{e}_2)$ be an orthonormal basis for T_o . Now parallel transport $\mathbf{e}_1$ along K , and let $\theta_{\parallel}$ denote the angle between this parallel-transported $\mathbf{e}_1$ and $\mathbf{v}$.

(i) Explain why $\mathbf{e}_2$ is automatically parallel-transported along K , too:

$$D_{\mathbf{v}} \mathbf{e}_1 = 0 \implies D_{\mathbf{v}} \mathbf{e}_2 = 0.$$

The angle between $\mathbf{e}_1$ and $\mathbf{e}_2$ is fixed at $\pi/2$. In ¶ 1, p. 233, it is explained that parallel transport requires that the direction of a vector $\mathbf{w}$ at each moment is always parallel to its direction a moment before. Since both $\mathbf{e}_1$ and $\mathbf{e}_2$ lie in the same plane and their angle is fixed, parallel transport of one implies parallel transport of the other.

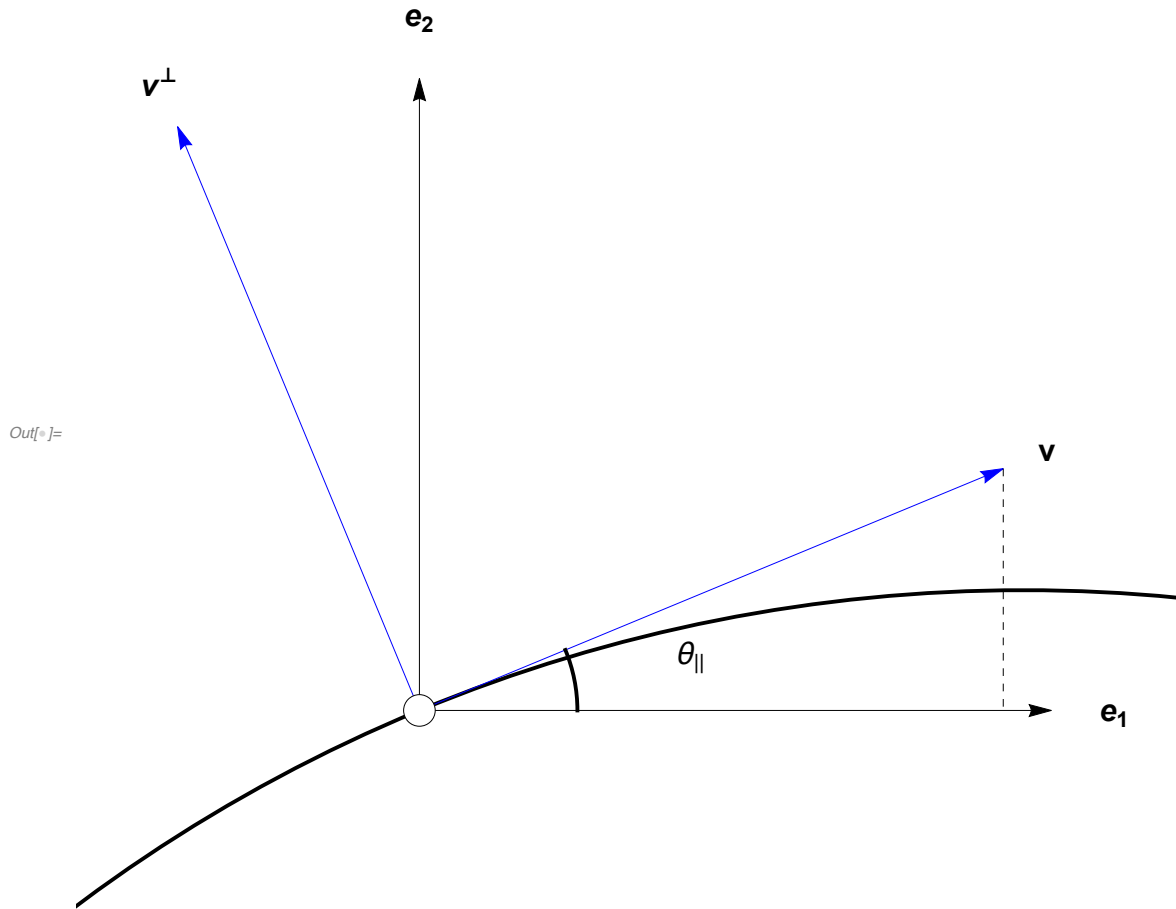


Figure 1. Rotation of vector $\mathbf{v}$ by $(\pi/2)$ within T_p

(ii) Let $\mathbf{v}^\perp$ be the unit vector obtained by rotating $\mathbf{v}$ by $(\pi/2)$ within T_p . Write $\mathbf{v}$ and $\mathbf{v}^\perp$ in terms of $(\mathbf{e}_1, \mathbf{e}_2)$. Now use calculation to prove that

$$\kappa_g = D_{\mathbf{v}} \mathbf{v} = [D_{\mathbf{v}} \theta_{\parallel}] \mathbf{v}^\perp.$$

Since we know that the bases $(\mathbf{e}_1, \mathbf{e}_2)$ are orthonormal, putting them on the x and y axes should cause no loss of generality. From part (i), we know that $\mathbf{e}_1$ is parallel-transported along K , so $\mathbf{e}_2$, which has a fixed angle with $\mathbf{e}_1$, must also be parallel-transported. Hence, the frame itself is parallel-transported. From (23.3), p. 244, we know that $\kappa_g = D_{\mathbf{v}} \mathbf{v}$. From Figure 1, let

$$\mathbf{v} = \cos\theta_{\parallel} \mathbf{e}_1 + \sin\theta_{\parallel} \mathbf{e}_2$$

$$\mathbf{v}^{\perp} = -\sin\theta_{\parallel} \mathbf{e}_1 + \cos\theta_{\parallel} \mathbf{e}_2 \quad (\text{because } \cos(\theta_{\parallel} + \pi/2) = -\sin\theta_{\parallel} \text{ and } \sin(\theta_{\parallel} + \pi/2) = \cos\theta_{\parallel}).$$

Then, following the first and third identities on p. 243, and using the results of part (i),

$$\begin{aligned} D_{\mathbf{v}} \mathbf{v} &= D_{\mathbf{v}}(\cos\theta_{\parallel} \mathbf{e}_1 + \sin\theta_{\parallel} \mathbf{e}_2) = D_{\mathbf{v}}(\cos\theta_{\parallel} \mathbf{e}_1) + D_{\mathbf{v}}(\sin\theta_{\parallel} \mathbf{e}_2). \\ &= D_{\mathbf{v}}(\cos\theta_{\parallel}) \mathbf{e}_1 + \cos\theta_{\parallel} D_{\mathbf{v}} \mathbf{e}_1 + D_{\mathbf{v}}(\sin\theta_{\parallel}) \mathbf{e}_2 + \sin\theta_{\parallel} D_{\mathbf{v}} \mathbf{e}_2 \\ &= -\sin\theta_{\parallel}(\theta_{\parallel})' \mathbf{e}_1 + \cos\theta_{\parallel} \cdot 0 + \cos\theta_{\parallel}(\theta_{\parallel})' \mathbf{e}_2 + \sin\theta_{\parallel} \cdot 0 = -\sin\theta_{\parallel}(\theta_{\parallel})' \mathbf{e}_1 + \cos\theta_{\parallel}(\theta_{\parallel})' \mathbf{e}_2 \quad (\text{see (i)}) \\ &= (\theta_{\parallel})' (-\sin\theta_{\parallel} \mathbf{e}_1 + \cos\theta_{\parallel} \mathbf{e}_2) = [D_{\mathbf{v}} \theta_{\parallel}] (-\sin\theta_{\parallel} \mathbf{e}_1 + \cos\theta_{\parallel} \mathbf{e}_2) \\ &= [D_{\mathbf{v}} \theta_{\parallel}] \mathbf{v}^{\perp} \end{aligned}$$

I wondered about the significance of the square brackets on the RHS. On p. 243, on the LHS, they serve to indicate “apply” or “ $\circ$ ”. Perhaps curved brackets would have served as well on the RHS: $(D_{\mathbf{v}} \theta_{\parallel}) \mathbf{v}^{\perp}$.

$\kappa_g = D_{\mathbf{v}} \mathbf{v}$ is proven by the zero value of the surface normal curvature κ_n in (23.3), p. 243 and p. 244.

Then, since $D_{\mathbf{v}} \mathbf{v} = (D_{\mathbf{v}} \theta_{\parallel}) \mathbf{v}^{\perp}$, and $\mathbf{v}^{\perp}$ is a unit vector, the magnitude $|\kappa_g|$ must be given by $|D_{\mathbf{v}} \theta_{\parallel}|$, thereby proving (23.4).

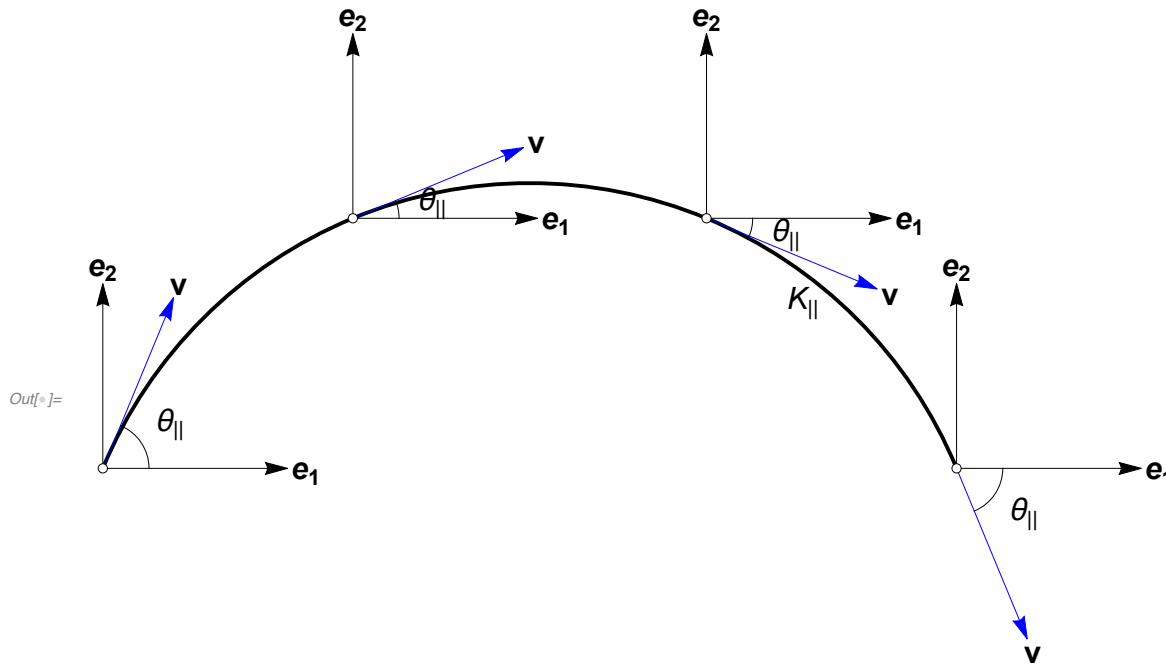


Figure 2. Surface curve K pressed flat to $K_{||}$
and traversed clockwise at unit speed

(iii) Draw a sketch illustrating $\mathbf{v}$, $(\mathbf{e}_1, \mathbf{e}_2)$, and $\theta_{||}$ at several points along K , after the narrow strip of peel surrounding K has been removed from S and pressed flat onto the plane.

See Figure 2. K has been removed and pressed flat to become $K_{||}$, which, by sheer chance, happened to have a circular shape.

(iv) Deduce that the geodesic curvature of K is indeed the ordinary curvature of the plane curve obtained by flattening the narrow strip surrounding K .

The proposition can be deduced from $\kappa_g = D_{\mathbf{v}} \mathbf{v} = [D_{\mathbf{v}} \theta_{||}] \mathbf{v}^{\perp}$. The expression $D_{\mathbf{v}} \theta_{||}$ represents change in an angle between the tangent and a parallel transported vector on successive tangent planes as p traverses a surface curve. When the curve is pressed onto a flat, Euclidean plane, the tangent planes are also pressed into and superimposed on the E plane. When the angular changes at each point are multiplied by $\mathbf{v}^{\perp}$, the result is a component orthogonal to velocity. It is the acceleration, which is equivalent to the “ordinary” curvature in the plane.

Comment: On a surface a “straight” line is a geodesic. So “geodesic curvature” actually measures departure of $\mathbf{v}$ from the direction of a geodesic. This can be a point of confusion. A *geodesic curve* has zero geodesic curvature, but *geodesic curvature* is not limited to geodesic curves. If a surface curve pressed or projected onto the plane shows measurable or visible positive or negative curvature κ on the

plane, one can call that the intrinsic geodesic curvature.